SUSE Storage Sizing and Performance for Ceph

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What is Ceph?

From 10,000 Meters

- Open Source Storage Distributed solution
- Most popular choice of distributed storage for openStack^[1]
- \cdot Lots of goodies
 - Distributed Object Storage
 - Redundancy
 - Efficient Scale-Out
 - Can be built on commodity hardware
 - Lower operational cost

[1] http://www.openstack.org/blog/2013/11/openstack-user-survey-statistics-november-2013/



From 1,000 Meters

- \cdot Three interfaces rolled into one
 - Object Access (like Amazon S3)
 - Block Access
 - (Distributed File System)
- \cdot Sitting on top of a Storage Cluster
 - Self Healing
 - Self Managed
 - No Bottlenecks



From 1,000 Meters

Unified Data Handling for 3 Purposes



Autonomous, Redundant Storage Cluster

Component Names





How Does Ceph Work?

For a Moment, Zooming to Atom Level



- OSDs serve storage objects to clients
- Peer to perform replication and recovery



Put Several of These in One Node





Mix In a Few Monitor Nodes

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- Monitors are the brain cells of the cluster
 Cluster Membership
 - Consensus for Distributed Decision Making
- · Do not serve stored objects to clients



Voilà, a Small RADOS Cluster





Several Ingredients

\cdot Basic Idea

- Coarse grained partitioning of storage supports policy based mapping (don't put all copies of my data in one rack)
- Topology map and Rules allow clients to "compute" the exact location of any storage object
- \cdot Three conceptual components
 - Pools
 - Placement groups
 - CRUSH: deterministic decentralized placement algorithm



Pools

- \cdot A pool is a logical container for storage objects
- · A pool has a set of parameters
 - a name
 - a numerical ID (internal to RADOS)
 - number of replicas OR erasure encoding settings
 - number of placement groups
 - placement rule set
 - owner
- Pools support certain operations
 - create/remove/read/write entire objects
 - snapshot of the entire pool



Placement Groups

- Placement groups help balance data across OSDs
- · Consider a pool named "swimmingpool"
 - with a pool ID of 38 and 8192 placement groups (PGs)
- Consider object "rubberduck" in "swimmingpool"
 - hash("rubberduck") % 8192 = 0xb0b
 - The resulting PG is 38.b0b
- \cdot One PG typically spans several OSDs
 - for balancing
 - for replication
- One OSD typically serves many PGs



CRUSH

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- CRUSH uses a map of all OSDs in your cluster
 - includes physical topology, like row, rack, host
 - includes rules describing which OSDs to consider for what type of pool/PG
- This map is maintained by the monitor nodes
 - Monitor nodes use standard cluster algorithms for consensus building, etc



CRUSH in Action: Reading





CRUSH in Action: Writing



Software Defined Storage

Legacy Storage Arrays

- Limits:
 - Tightly controlled environment
 - Limited scalability
 - Few options
 - Only certain approved drives
 - Constrained number of disk slots
 - Few memory variations
 - Only very few networking choices
 - Typically fixed controller and CPU

- Benefits:
 - Reasonably easy to understand
 - Long-term experience and "gut instincts"
 - Somewhat deterministic behavior and pricing



Software Defined Storage (SDS)

- Limits:
 - ?

- Benefits:
 - Infinite scalability
 - Infinite adaptability
 - Infinite choices
 - Infinite flexibility

- ... right.



Properties of a SDS System

- Throughput
- Latency
- · IOPS

- Capacity
- Density

Availability

Reliability

· Cost



Architecting a SDS system

- These goals often conflict:
 - Availability versus Density
 - IOPS versus Density
 - Everything versus Cost
- Many hardware options
- Software topology offers many configuration choices
- $\boldsymbol{\cdot}$ There is no one size fits all



Setup Choices

Networking (Public and Private)

- Ethernet (1, 10, 40 GbE)
 - Reasonably inexpensive (except for 40 GbE)
 - Can easily be bonded for availability
 - Use jumbo frames
- · Infiniband
 - High bandwidth
 - Low latency
 - Typically more expensive
 - No support for RDMA yet in Ceph, need to use IPoIB



Network

- Choose the fastest network you can afford
- Switches should be low latency with fully meshed backplane
- Separate public and cluster network
- Cluster network should typically be twice the public bandwidth
 - Incoming writes are replicated over the cluster network
 - Re-balancing and re-mirroring take utilize the cluster network



Different Access Modes

- radosgw:
 - An additional gateway in front of your RADOS cluster
 - Little impact on throughput, but it does affect latency
- User-space RADOS access:
 - More feature rich than inkernel rbd.ko module
 - Typically provides higher performance



Storage Node

- · CPU
 - Number and speed of cores
- Memory
- Storage controller
 - Bandwidth, performance, cache size
- \cdot SSDs for OSD journal
 - SSD to HDD ratio
- \cdot HDDs
 - Count, capacity, performance



Adding More Nodes

- \cdot Capacity increases
- Total throughput increases
- IOPS increase
- \cdot Redundancy increases

- Latency unchanged
- Eventually: network topology limitations
- Temporary impact during re-balancing



Adding More Disks to a Node

- \cdot Capacity increases
- \cdot Redundancy increases
- Throughput might increase
- IOPS might increase

- Internal node bandwidth is consumed
- Higher CPU and memory load
- Cache contention
- Latency unchanged



OSD File System

btrfs

- Typically better write throughput performance
- Higher CPU utilization
- Feature rich
 - Compression, checksums, copy on write
- The choice for the future!

• XFS

- Good all around choice
- Very mature for data partitions
- Typically lower CPU utilization
- The choice for today!



Impact of Caches

- \cdot Cache on the client side
 - Typically, biggest impact on performance
 - Does not help with write performance
- \cdot Server OS cache
 - Low impact: reads have already been cached on the client
 - Still, helps with readahead
- Caching controller, battery backed:
 - Significant impact for writes



Impact of SSD Journals

- SSD journals accelerate bursts and random write IO
- For sustained writes that overflow the journal, performance degrades to HDD levels
- SSDs help very little with read performance
- SSDs are very costly
 - ... and consume storage slots -> lower density
- A large battery-backed cache on the storage controller is highly recommended if not using SSD journals



Hard Disk Parameters

- Capacity matters
 - Often, highest density is not most cost effective
- On-disk cache matters less
- Reliability advantage of Enterprise drives typically marginal compared to cost
 - Buy more drives instead

• RPM:

- Increase IOPS & throughput
- Increases power consumption
- 15k drives quite expensive still



Impact of Redundancy Choices

- Replication:
 - n number of exact, full-size copies
 - Potentially increased read performance due to striping
 - Increased cluster network utilization for writes
 - Rebuilds can leverage multiple sources
 - Significant capacity impact

- Erasure coding:
 - Data split into k parts plus m redundancy codes
 - Better space efficiency
 - Higher CPU overhead
 - Significant CPU and cluster network impact, especially during rebuild
 - Cannot directly be used to with block devices (see next slide)



Cache Tiering

- Multi-tier storage architecture:
 - Pool acts as a transparent write-back overlay for another
 - e.g., SSD 3-way replication over HDDs with erasure coding
 - Can flush either on relative or absolute dirty levels, or age
 - Additional configuration complexity and requires workloadspecific tuning
 - Also available: read-only mode (no write acceleration)
 - Some downsides (no snapshots)
- A good way to combine the advantages of replication and erasure coding



Conclusion

Questions and Answers?

Thank you.





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